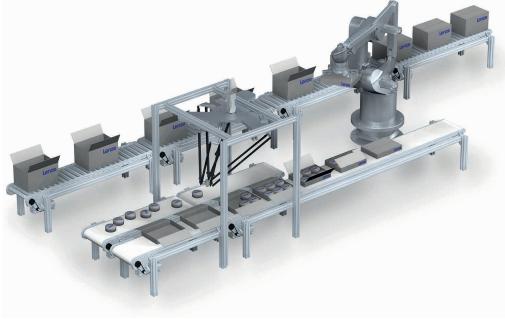
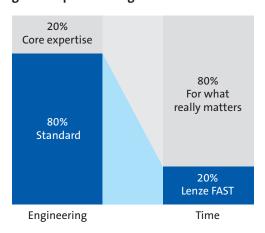
Get robots moving – it's easy.



FAST goes robotics: Ready-made robotics modules make it extremely easy to integrate kinematics into the entire automation process. Technology modules for Pick & Place applications are available for this purpose, with models designed for different kinds of kinematics. A fully functional robotics core is already integrated to ensure the greatest possible degree of freedom.



Highlights

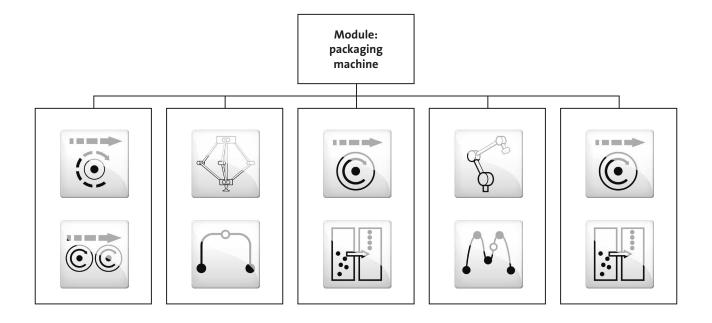
- Up to 80% of software engineering requirements are covered by Lenze FAST
- Spatial movements based on a powerful robotics core with six degrees of freedom
- Motion planning is based on PLCopen Part4, for all main and auxiliary axes
- Thanks to the encapsulated pathplanning system in the FAST technology module, no knowledge of robot programming is required
- Structured programming layout via the Application Template
- Software is rigorously tested for flawless operation



The robotics modules for your machine

Modular programming

When using FAST, automation controls engineers can program quickly using a basic architecture. The functions are encapsulated in the individual modules. The modules are autonomous and can easily be exchanged and tested completely independently. This makes engineering fast, easy and reliable.



| Lenze FAST | Description |
|---------------------------|--|
| Basic Motion | Basic functions for the drive |
| Virtual Master | Basic module for general machine tasks, virtual master axis in the machine |
| Electrical Shaft Position | Electrical Shaft Position Positioning products with accurate rotor position synchronization and coupling of axes |
| Electrical Shaft Velocity | Synchronizm across multiple stations, speed-accurate synchronization and coupling of axes |
| Pick & Place Basic | Create simple Pick & Place profiles with diverse kinematics, e.g. Delta3 robots |
| Pick & Place Advanced | Create Pick & Place profiles of up to 10 interpolation points with diverse kinematics, e.g. articulated robot |
| Tracking Management | Workpiece tracking and synchronizing |